Collective Effects

in

Equilibrium and Nonequilibrium Physics

Website: http://cnco.bnu.edu.cn/mccross/Course/

Caltech Mirror: http://haides.caltech.edu/BNU/
Today’s Lecture: Instability in Systems far from Equilibrium

Outline

• Closed and open systems
• Bénard’s experiment and Rayleigh’s theory
• Taylor-Couette instability
• Turing’s paper on morphogenesis
• General remarks on pattern forming instabilities
Heat Death of the Universe (from Wikepedia)

Heat death is a possible final state of the universe, in which it has “run down” to a state of no free energy to sustain motion or life. In physical terms, it has reached maximum entropy.

Origins of the idea

The idea of heat death stems from the second law of thermodynamics, which claims that entropy tends to increase in an isolated system.

If the universe lasts for a sufficient time, it will asymptotically approach a state where all energy is evenly distributed. Hermann von Helmholtz is thought to be the first to propose the idea of heat death in 1854, 11 years before Clausius’s definitive formulation of the Second law of thermodynamics in terms of entropy (1865).
An Open System
Pattern Formation

The spontaneous formation of spatial structure in open systems driven far from equilibrium
Equilibrium - Far From Equilibrium

\[ \Delta T \]

Perturbations grow

Far from equilibrium

\[ \Delta T_c \]

Perturbations decay

Equilibrium
Origins

1900  Bénard’s experiments on convection in a dish of fluid heated from below and with a free surface

1916  Rayleigh’s theory explaining the formation of convection rolls and cells in a layer of fluid with rigid top and bottom plates and heated from below

1923  Taylor’s experiment and theory on the instability of a fluid between an inner rotating cylinder and a fixed outer one

1952  Turing’s suggestion that instabilities in chemical reaction and diffusion equations might explain morphogenesis

1950s-60s  Belousov and Zhabotinskii work on chemical reactions showing oscillations and waves
Bénard’s Experiments

(Reproduced by Carsten Jäger)

Movie
Rayleigh’s Description of Bénard’s Experiments
Rayleigh’s Description of Bénard’s Experiments

• The layer rapidly resolves itself into a number of cells, the motion being an ascension in the middle of the cell and a descension at the common boundary between a cell and its neighbours.
Rayleigh’s Description of Bénard’s Experiments

• The layer rapidly resolves itself into a number of cells, the motion being an ascension in the middle of the cell and a descension at the common boundary between a cell and its neighbours.

• Two phases are distinguished, of unequal duration, the first being relatively short. The limit of the first phase is described as the “semi-regular cellular regime”; in this state all the cells have already acquired surfaces nearly identical, their forms being nearly regular convex polygons of, in general, 4 to 7 sides. The boundaries are vertical....
Rayleigh’s Description of Bénard’s Experiments

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• The second phase has for its limit a permanent regime of regular hexagons…. It is extremely protracted, if the limit is regarded as the complete attainment of regular hexagons. The tendency, however, seems sufficiently established.
Ideal Hexagonal Pattern

From the website of Michael Schatz
Rayleigh’s Simplifications

• The calculations which follow are based upon equations given by Boussinesq, who has applied them to one or two particular problems. The special limitation which characterizes them is the neglect of variations of density, except in so far as they modify the actions of gravity.
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- In the present problem the case is much more complicated, unless we arbitrarily limit it to two dimensions. The cells of Bénard are then reduced to infinitely long strips, and when there is instability we may ask for what wavelength (width of strip) the instability is greatest.
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• …and we have to consider boundary conditions. Those have been chosen which are simplest from the mathematical point of view, and they deviate from those obtaining in Bénard’s experiment, where, indeed, the conditions are different at the two boundaries.
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Rayleigh and his Solution
Schematic of Instability

Fluid

Rigid plate

Rigid plate
Schematic of Instability

Fluid

Rigid plate

Rigid plate
Schematic of Instability
Schematic of Instability
Schematic of Instability
Equations for Fluid and Heat Flow

Mass conservation (LL1.2)

\[ \frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{g} = 0 \quad \text{with} \quad \mathbf{g} = \rho \mathbf{v} \]

Momentum conservation (LL15.1)

\[ \frac{\partial (\rho \mathbf{v})}{\partial t} + \nabla \cdot \mathbf{\Pi} + \rho \mathbf{g} \hat{\mathbf{z}} = 0 \quad \text{or} \quad \frac{\partial (\rho v_i)}{\partial t} + \nabla_j \Pi_{ij} - \rho g_{iz} = 0 \]

with (LL15.3)

\[ \Pi_{ij} = p \delta_{ij} + \rho v_i v_j - \eta \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} - \frac{2}{3} \delta_{ij} \frac{\partial v_i}{\partial x_i} \right) - \zeta \delta_{ij} \frac{\partial v_i}{\partial x_i} \]

Entropy production (LL49.5-6)

\[ \frac{\partial (\rho s)}{\partial t} + \nabla \cdot (\rho s \mathbf{v} - \frac{K}{T} \nabla T) = \frac{K (\nabla T)^2}{T^2} + \frac{\eta}{2T} \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} - \frac{2}{3} \delta_{ij} \frac{\partial v_i}{\partial x_i} \right)^2 + \frac{\zeta}{T} \left( \frac{\partial v_i}{\partial x_i} \right)^2 \]
Buoyancy Force

- Assume density is just a function of the temperature, and expand about reference temperature $T_0$

$$\rho = \rho_0[1 - \alpha(T - T_0)]$$
**Buoyancy Force**

- Assume density is just a function of the temperature, and expand about reference temperature $T_0$

\[
\rho = \rho_0[1 - \alpha(T - T_0)]
\]

- Momentum equation becomes

\[
\frac{\partial (\rho \mathbf{v})}{\partial t} + \nabla \cdot \mathbf{\Pi} - \rho_0\alpha g(T - T_0)\mathbf{\hat{z}} = 0
\]

with $\mathbf{\Pi}$ as before except for a redefined pressure $\tilde{p} = p + \rho_0 g z$
Buoyancy Force

- Assume density is just a function of the temperature, and expand about reference temperature $T_0$

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with $\mathbf{\Pi}$ as before except for a redefined pressure $\bar{p} = p + \rho_0 g z$

- After finding the buoyancy force we assume the fluid is incompressible.
Buoyancy Force

- Assume density is just a function of the temperature, and expand about reference temperature $T_0$

$$\rho = \rho_0 [1 - \alpha(T - T_0)]$$

- Momentum equation becomes

$$\frac{\partial (\rho \mathbf{v})}{\partial t} + \nabla \cdot \mathbf{\Pi} - \rho_0 \alpha g (T - T_0) \mathbf{\hat{z}} = 0$$

with $\mathbf{\Pi}$ as before except for a redefined pressure $\tilde{p} = p + \rho_0 g z$

- After finding the buoyancy force we assume the fluid is incompressible.

- Also approximate specific heat, viscosity, thermal conductivity as constants (independent of temperature)
Boussinesq Equations

Mass conservation

\[
\frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{g} = 0 \quad \text{with} \quad \mathbf{g} = \rho \mathbf{v}
\]
Boussinesq Equations

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with
\[ \Pi_{ij} = \tilde{\rho} \delta_{ij} + \rho v_i v_j - \eta \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} - \frac{2}{3} \delta_{ij} \frac{\partial v_k}{\partial x_k} \right) - \zeta \delta_{ij} \frac{\partial v_i}{\partial x_i} \]
Boussinesq Equations

Mass conservation

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$$\nabla \cdot \mathbf{v} = 0$$

Momentum conservation

$$\frac{\partial (\rho \mathbf{v})}{\partial t} + \nabla \cdot \mathbf{P} - \rho_0 \alpha g (T - T_0) \hat{Z} = 0$$

or

$$\frac{\partial (\rho v_i)}{\partial t} + \nabla_j \Pi_{ij} - \rho_0 \alpha g (T - T_0) \delta_{iz} = 0$$

with

$$\Pi_{ij} = \bar{p} \delta_{ij} + \rho v_i v_j - \eta \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} - \frac{2}{3} \delta_{ij} \frac{\partial v_i}{\partial x_i} \right) - \zeta \delta_{ij} \frac{\partial v_i}{\partial x_i}$$

$$\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} = -\nabla (\bar{p}/\rho_0) + \rho_0 \alpha g (T - T_0) \hat{Z} + \nu \nabla^2 \mathbf{v}$$

with

$$\nu = \eta/\rho_0$$
Entropy production

\[
\frac{\partial (\rho s)}{\partial t} + \nabla \cdot (\rho s \mathbf{v} - \frac{K}{T} \nabla T) = \frac{K (\nabla T)^2}{T^2} + \frac{\eta}{2T} \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} - \frac{2}{3} \delta_{ij} \frac{\partial v_i}{\partial x_i} \right)^2 + \frac{\zeta}{T} \left( \frac{\partial v_i}{\partial x_i} \right)^2
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$$\frac{\partial T}{\partial t} + \mathbf{v} \cdot \nabla T = \kappa \nabla^2 T \quad \text{with} \quad ds \rightarrow C dT \quad \text{and} \quad \kappa = \frac{K}{C}$$
**Boussinesq Equations**

Mass conservation (incompressibility)
\[ \nabla \cdot \mathbf{v} = 0 \]

Momentum conservation
\[ \frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} = -\nabla (\bar{p}/\rho_0) + \alpha g (T - T_0) \hat{z} + \nu \nabla^2 \mathbf{v} \quad \text{with} \quad \nu = \eta/\rho_0 \]

Entropy production/heat flow
\[ \frac{\partial T}{\partial t} + \mathbf{v} \cdot \nabla T = \kappa \nabla^2 T \quad \text{with} \quad ds \rightarrow C dT \quad \text{and} \quad \kappa = K/C \]
Boussinesq Equations

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Conducting solution (\( \mathbf{v} = 0 \))
\[ T_{\text{cond}} = T_0 - \Delta T z/d \]
\[ \bar{p}_{\text{cond}} = p_0 - \alpha g \rho_0 \Delta T z^2/2d \]
Lesson from Fluid Mechanics: Dedimensionalize

\[ x' = x/d \]
\[ t' = t/(d^2/\kappa) \]
\[ v' = v/(\kappa/d) \]
\[ \theta' = (T - T_{\text{cond}})/(\kappa v/\alpha gd^3) \]
\[ p' = (\bar{p} - \bar{p}_{\text{cond}})/(\rho_0\kappa v/d^2) \]
Lesson from Fluid Mechanics: Dedimensionalize

\[ x' = \frac{x}{d} \]
\[ t' = \frac{t}{(d^2 / \kappa)} \]
\[ v' = \frac{v}{(\kappa / d)} \]
\[ \theta' = \frac{(T - T_{\text{cond}})}{(\kappa v / \alpha g d^3)} \]
\[ p' = \frac{(\bar{p} - \bar{p}_{\text{cond}})}{(\rho_0 \kappa v / d^2)} \]

Note that

\[ v \cdot \nabla T \Rightarrow \text{const} \times (v' \cdot \nabla' \theta' - Rw') \]

(with \( R = \frac{\alpha g d^3 \Delta T}{\kappa v} \))

(writing \( v = (u, v, w) \))
Scaled Equations for Fluid and Heat Flow

Go to primed variables (and then drop the primes)
Scaled Equations for Fluid and Heat Flow

Go to primed variables (and then drop the primes)

Mass conservation (incompressibility)

\[ \nabla \cdot \mathbf{v} = 0 \]

Momentum conservation

\[ \mathcal{P}^{-1} \left( \frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = -\nabla p + \theta \hat{z} + \nabla^2 \mathbf{v} \]

Entropy production/heat flow

\[ \frac{\partial \theta}{\partial t} + \mathbf{v} \cdot \nabla \theta = R w + \nabla^2 \theta \]

Dimensionless ratios: Prandtl number \( \mathcal{P} = v/\kappa \); Rayleigh number \( R = \alpha gd^3 \Delta T / \kappa v \)

Boundary conditions at top and bottom plates \( z = \pm \frac{1}{2} \)

- Fixed temperature \( \theta = 0 \)
- Zero velocity (no slip) \( \mathbf{v} = 0 \)
Rayleigh’s Calculation

\[ \nabla \cdot \mathbf{v} = 0 \]

\[ \mathcal{P}^{-1} \frac{\partial \mathbf{v}}{\partial t} = -\nabla p + \theta \hat{z} + \nabla^2 \mathbf{v} \]

\[ \frac{\partial \theta}{\partial t} = R w + \nabla^2 \theta \]

Boundary conditions at top and bottom plates \( z = \pm \frac{1}{2} \)

Fixed temperature \( \theta = 0 \)

Free slip for \( \mathbf{v} = (u, v, w) \) \( w = \partial u/\partial z = \partial v/\partial z = 0 \)

Two dimensional mode, exponential time dependence

\[ w = w_0 e^{\sigma t} \cos(q x) \cos(\pi z) \]

\[ u = w_0 e^{\sigma t} (\pi/q) \sin(q x) \sin(\pi z) \]

\[ \theta = \theta_0 e^{\sigma t} \cos(q x) \cos(\pi z) \]

gives

\[ (\pi^2 + q^2)(\mathcal{P}^{-1} \sigma + \pi^2 + q^2)(\sigma + \pi^2 + q^2) - R q^2 = 0 \]
Rayleigh’s Growth Rate (for $\mathcal{P} = 1$)

$$R = R_c, \quad q = q_c$$

$$\sigma$$

$$q/\pi$$

$$R = 0.5 R_c$$

$$R = R_c$$

$$R = 1.5 R_c$$

$$R_c = \frac{27\pi^4}{4}, \quad q_c = \frac{\pi}{\sqrt{2}}$$
Rayleigh’s Growth Rate (for $P = 1$)

$$R_c = \frac{27\pi^4}{4}, \quad q_c = \frac{\pi}{\sqrt{2}}$$
Comments

• Rayleigh seems to have been unaware that a hexagonal state is easily produced as a sum of three stripe states with wave vectors \( q(1, 0), q(-1/2, \sqrt{3}/2), q(-1/2, -\sqrt{3}/2) \). Since the calculation is linear the principle of superposition applies, and the growth rate and \( R_c, q_c \) are the same for hexagons as for stripes.
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• Rayleigh had the insight that the nonlinear terms would be important in pattern selection:

The second phase of Bénard, where a tendency reveals itself for a slow transformation into regular hexagons, is not touched. It would seem to demand the inclusion of the squares of quantities here treated as small.
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• The linear instability with rigid plates with physical (no-slip) boundaries is harder because the equations are not separable. A handout on the website works through the calculation. The qualitative results are similar, but now $R_c \approx 1707$ and $q_c \approx 3.114$ ($q_c = \pi$ would give rolls with diameter equal the depth).
Taylor-Couette Instability

From the website of Arel Weisberg
Taylor’s 1923 Results: Onset

Taylor’s 1923 Results: Wavenumber

The outer and inner radii were $r_0 = 4.04$ cm, and $r_i = 3.80$ cm. $\mu$ is the ratio of outer to inner rotation rates $\Omega_2 / \Omega_1$. The vertical label $d/\theta$ is the average width of a vortex in centimeters.
Turing: The Chemical Basis of Morphogenesis

Wikipedia: Morphogenesis (from the Greek morphê shape and genesis creation) is one of three fundamental aspects of developmental biology.... The study of morphogenesis involves an attempt to understand the processes that control the organized spatial distribution of cells that arises during the embryonic development of an organism and which give rise to the characteristic forms of tissues, organs and overall body anatomy.

Turing (Phil. Tran. R. Soc. Lon. B237, 37 (1952)): It is suggested that a system of chemical substances, called morphogens, reacting together and diffusing through a tissue, is adequate to account for the main phenomena of morphogenesis. Such a system, although it may originally be quite homogeneous, may later develop a pattern or structure due to an instability of the homogeneous equilibrium, which is triggered off by random disturbances.
Quotes from Turing’s Paper

This model will be a simplification and an idealization, and consequently a falsification. It is to be hoped that the features retained for discussion are those of greatest importance in the present state of knowledge.

One would like to be able to follow this more general [nonlinear] process mathematically also. The difficulties are, however, such that one cannot hope to have any very embracing theory of such processes, beyond the statement of the equations. It might be possible, however, to treat a few particular cases in detail with the aid of a digital computer.
Turing on Broken Symmetry

There appears superficially to be a difficulty confronting this theory of morphogenesis, or, indeed, almost any other theory of it. An embryo in its spherical blastula stage has spherical symmetry.... But a system which has spherical symmetry, and whose state is changing because of chemical reactions and diffusion, will remain spherically symmetrical for ever..... It certainly cannot result in an organism such as a horse, which is not spherically symmetrical.

There is a fallacy in this argument. It was assumed that the deviations from spherical symmetry in the blastula could be ignored because it makes no particular difference what form of asymmetry there is. It is, however, important that there are some deviations, for the system may reach a state of instability in which these irregularities, or certain components of them, tend to grow.....In practice, however, the presence of irregularities, including statistical fluctuations in the numbers of molecules undergoing the various reaction, will, if the system has an appropriate kind of instability, result in this homogeneity disappearing.
Mathematical Content of Turing’s Paper

- Linear stability analysis of:
  - Ring of discrete cells
  - Ring of continuous medium
  - Surface of sphere

- Discussion of types of instabilities:
  - uniform instabilities (wave number $q_c = 0$)
  - instabilities leading to spatial structure ($q_c \neq 0$)
  - oscillatory instabilities (2 chemicals) ($q_c = 0$, $\text{Im} \sigma \neq 0$)
  - wave instabilities ($q_c \neq 0$, $\text{Im} \sigma \neq 0$) (3 or more chemicals)

- Evolution from random initial condition in 1 and 2 dimensions
- Manual computation of nonlinear state in small discrete rings
**Reaction-Diffusion**

Two chemical species with concentrations $u_1$, $u_2$ that react and diffuse

\[
\begin{align*}
\partial_t u_1 &= f_1 (u_1, u_2) + D_1 \partial_x^2 u_1 \\
\partial_t u_2 &= f_2 (u_1, u_2) + D_2 \partial_x^2 u_2
\end{align*}
\]
Reaction-Diffusion

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- Reaction:

$$a \, A + b \, B \rightarrow c \, C + d \, D$$

gives the reaction rate (law of mass action)

$$\nu(t) = -\frac{1}{a} \frac{d[A]}{dt} = \cdots = k[A]^{m_A}[B]^{m_B}$$

with $m_A = a \ldots$ for elementary reactions
Reaction-Diffusion

Two chemical species with concentrations $u_1, u_2$ that react and diffuse

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- Reaction:

$$a \, A + b \, B \rightarrow c \, C + d \, D$$

gives the reaction rate (law of mass action)

$$v(t) = -\frac{1}{a} \frac{d[A]}{dt} = \cdots = k[A]^{m_A}[B]^{m_B}$$

with $m_A = a \ldots$ for elementary reactions

- Diffusion: conservation equation

$$\partial_t u_i = -\nabla \cdot j_i$$

with

$$j_i = -D_i \nabla u_i$$

(Skip to example)
Turing Instability

- Stationary uniform base solution $u_b = (u_{1b}, u_{2b})$

\[
\begin{align*}
    f_1(u_{1b}, u_{2b}) &= 0 \\
    f_2(u_{1b}, u_{2b}) &= 0
\end{align*}
\]
Turing Instability

• Stationary uniform base solution \( \mathbf{u}_b = (u_{1b}, u_{2b}) \)

\[
\begin{align*}
\quad f_1(u_{1b}, u_{2b}) &= 0 \\
\quad f_2(u_{1b}, u_{2b}) &= 0
\end{align*}
\]

• Linearize about the base state \( \mathbf{u} = \mathbf{u}_b + \delta \mathbf{u} \)

\[
\begin{align*}
\partial_t \delta u_1 &= a_{11} \delta u_1 + a_{12} \delta u_2 + D_1 \partial_x^2 \delta u_1 \\
\partial_t \delta u_2 &= a_{21} \delta u_1 + a_{22} \delta u_2 + D_2 \partial_x^2 \delta u_2
\end{align*}
\]

with \( a_i = \frac{\partial f_i}{\partial u_j} \bigg|_{\mathbf{u}=\mathbf{u}_b} \).
Turing Instability

- Stationary uniform base solution $u_b = (u_{1b}, u_{2b})$
  
  \[ f_1(u_{1b}, u_{2b}) = 0 \]
  \[ f_2(u_{1b}, u_{2b}) = 0 \]

- Linearize about the base state $u = u_b + \delta u$

  \[ \partial_t \delta u_1 = a_{11} \delta u_1 + a_{12} \delta u_2 + D_1 \partial_x^2 \delta u_1 \]
  \[ \partial_t \delta u_2 = a_{21} \delta u_1 + a_{22} \delta u_2 + D_2 \partial_x^2 \delta u_2 \]

  with $a_i = \partial f_i / \partial u_j |_{u = u_b}$.

- Seek a solution $\delta u(t, x)$ that is a Fourier mode with exponential time dependence:

  \[ \delta u = \delta u_q e^{\sigma_q t} e^{i q x} = \begin{pmatrix} \delta u_{1q} \\ \delta u_{2q} \end{pmatrix} e^{\sigma_q t} e^{i q x} \]
Stability Analysis

- Eigenvalue equation

\[ A_q \delta u_q = \sigma_q \delta u_q \]

where

\[ A_q = \begin{pmatrix} a_{11} - D_1q^2 & a_{12} \\ a_{21} & a_{22} - D_2q^2 \end{pmatrix} \]
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- Eigenvalues are

\[ \sigma_q = \frac{1}{2} \text{tr} \mathbf{A}_q \pm \frac{1}{2} \sqrt{(\text{tr} \mathbf{A}_q)^2 - 4 \det \mathbf{A}_q} \]
Stability Regions

- Stable
  - $\text{Re} \sigma_{1,2} < 0$
  - $\text{Im} \sigma_{1,2} \neq 0$

- Oscillatory
  - $\text{Re} \sigma_{1,2} > 0$
  - $\text{Im} \sigma_{1,2} \neq 0$

- Stationary
  - $\text{Im} \sigma_{1,2} = 0$
  - $\text{Re} \sigma_{1,2} > 0$

- $\text{Im} \sigma_{1,2} = 0$
  - $\text{Re} \sigma_1 > 0$
  - $\text{Re} \sigma_2 < 0$
Conditions for Turing Instability

- Uniform state is stable to a spatially uniform instability

\[ a_{11} + a_{22} < 0 \]
\[ a_{11}a_{22} - a_{12}a_{21} > 0 \]
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(Take \( a_{22} < 0 \).)
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(Take \( a_{22} < 0 \).)

- Stationary instability at nonzero wave number (\( \text{Im} \sigma_{q_c} = 0, q_c \neq 0 \))

\[
D_1 a_{22} + D_2 a_{11} > 2\sqrt{D_1 D_2 (a_{11}a_{22} - a_{12}a_{21})}
\]

and at the wave number

\[
q_m^2 = \frac{1}{2} \left( \frac{a_{11}}{D_1} + \frac{a_{22}}{D_2} \right)
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• (Now we see \( a_{11} > 0 \) and \( a_{12}, a_{21} \) must have opposite signs)
Turing Length Scale

Turing condition can be expressed as

\[ q_m^2 = \frac{1}{2} \left( \frac{1}{l_1^2} - \frac{1}{l_2^2} \right) > \sqrt{\frac{a_{11}a_{22} - a_{12}a_{21}}{D_1D_2}} \]

with \( l_i = \sqrt{D_i/a_{ii}} \) are diffusion lengths: “local activation with long range inhibition”
Example: the Brusselator

\[ \partial_t u_1 = a - (b + 1)u_1 + u_1^2 u_2 + D_1 \partial_x^2 u_1 \]
\[ \partial_t u_2 = bu_1 - u_1^2 u_2 + D_2 \partial_x^2 u_2 \]

Example parameter values: \( a = 1.5, \quad D_1 = 2.8, \quad D_2 = 22.4 \)
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\end{pmatrix}
\]

- Seek a solution \( \delta u(t, x) \) that is a Fourier mode with exponential time dependence:

\[
\delta u = \delta u_q e^{\sigma_q t} e^{iqx} = (\delta u_{1q}, \delta u_{2q}) e^{\sigma_q t} e^{iqx}
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  \[ \delta \mathbf{u} = \delta \mathbf{u}_q e^{\sigma_q t} e^{iqx} = (\delta u_{1q}, \delta u_{2q}) e^{\sigma_q t} e^{iqx} \]
- Instability for \( b \geq b_c \) at wave number \( q_c \) with
  \[
  b_c = \left( 1 + a \sqrt{\frac{D_1}{D_2}} \right)^2 \approx 2.34, \quad q_c = \sqrt{\frac{D_1 a_{22} + D_2 a_{11}}{2D_1D_2}} \approx 0.435
  \]
Brusselator: Results
Brusselator: Results

![Graph showing Brusselator results with parameters and critical point indicated.]

Re $\sigma_q$ vs $q$

$q_-$ for $b = 1.4b_c$

$q_+$ for $b = 1.4b_c$
Onset in Systems with Rotational Symmetry

Growth Rate

$q_x$, $q_y$
Pattern Formation

\[ q_x \]
\[ q_y \]
\[ q_+ \]
\[ q_- \]
\[ q_c \]
\[ \sigma > 0 \]
Pattern Formation

What states form from the nonlinear saturation of the unstable modes?
Stripe state

$q_x$
Square state
Rectangular (orthorhombic) state
Hexagonal state
Supersquare state
Superhexagon state
Quasicrystal state
Next Lecture

Pattern Formation: Nonlinearity and Symmetry

- Amplitude equations
- Symmetry, the phase variable and rigidity
- Topological defects